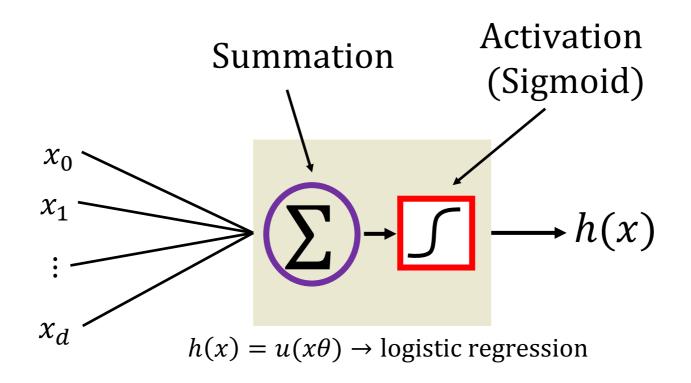
Machine Learning CS 4641

CONVOLUTIONAL NEURAL NETWORK

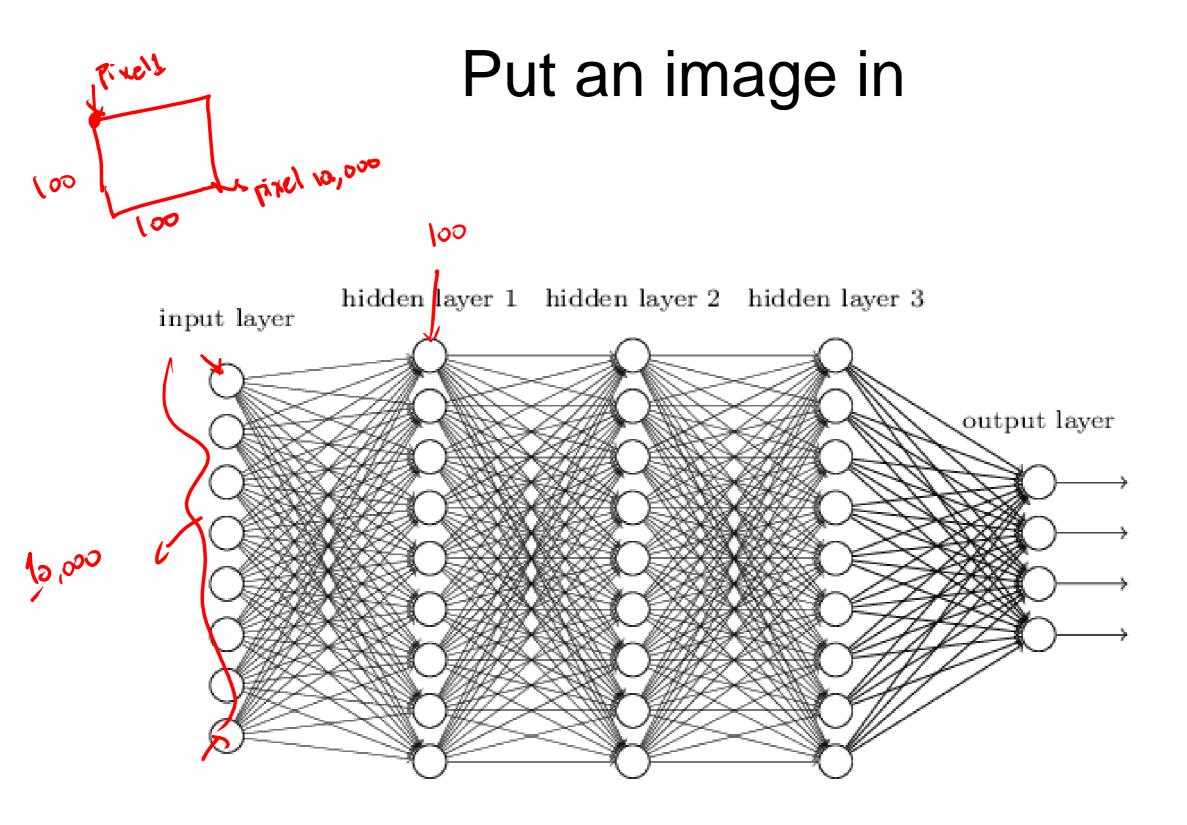
Nakul Gopalan Georgia Tech

Slides are based on Ming Li and Mahdi Roozbahani



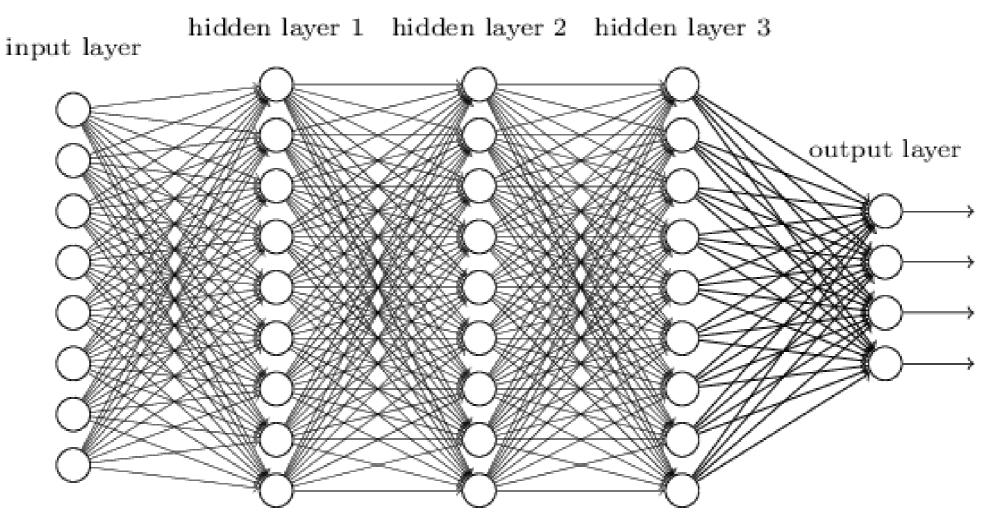
 $output = activation(x\theta + b)$

Name of the neuron	Activation function: <i>activation</i> (<i>z</i>)		
Linear unit	xθ		
Threshold/sign unit	sign(x θ)		
Sigmoid unit	$\frac{1}{1 + \exp(-x\theta)}$		
Rectified linear unit (ReLU)	$\max(0, x\theta)$		
Tanh unit	$tanh(x\theta)$		



Smaller Network: CNN

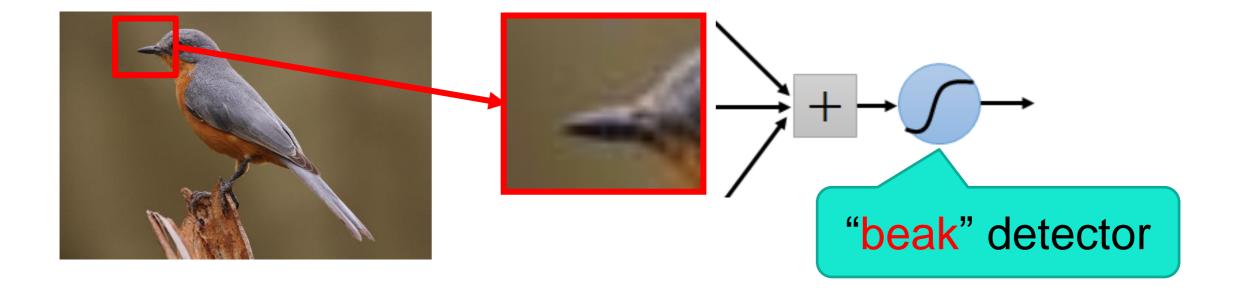
- We know it is good to learn a small model.
- From this fully connected model, do we really need all the edges?
- Can some of these be shared?



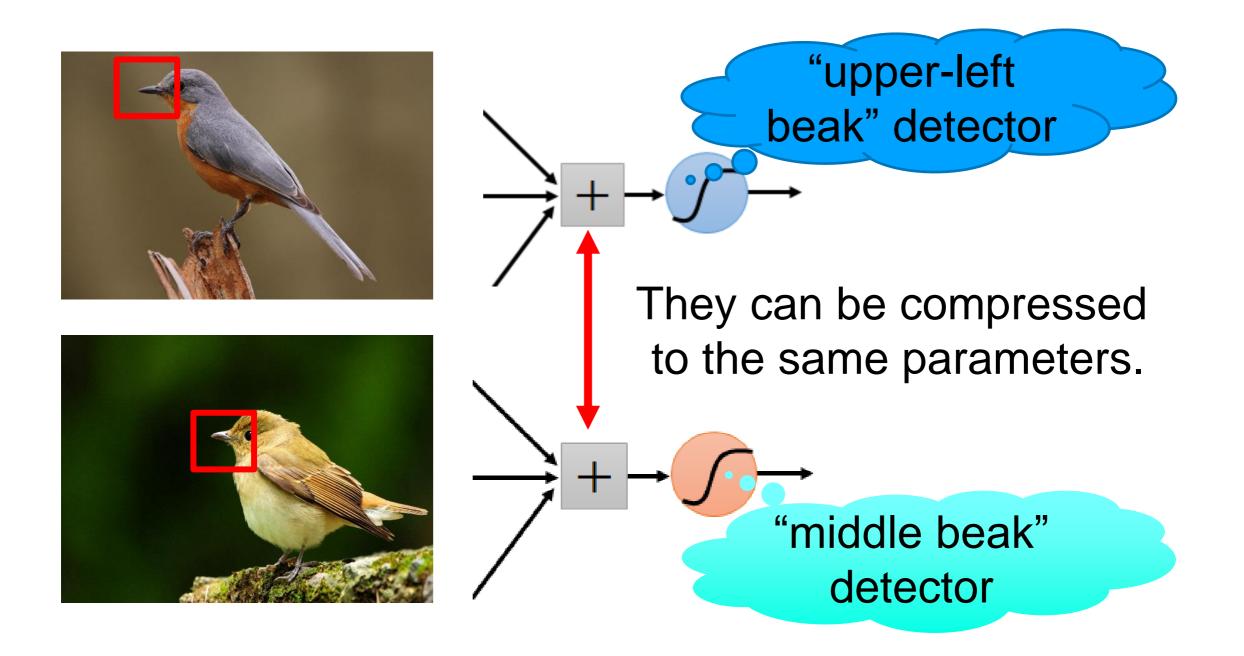
Consider learning an image:

• Some patterns are much smaller than the whole image

Can represent a small region with fewer parameters

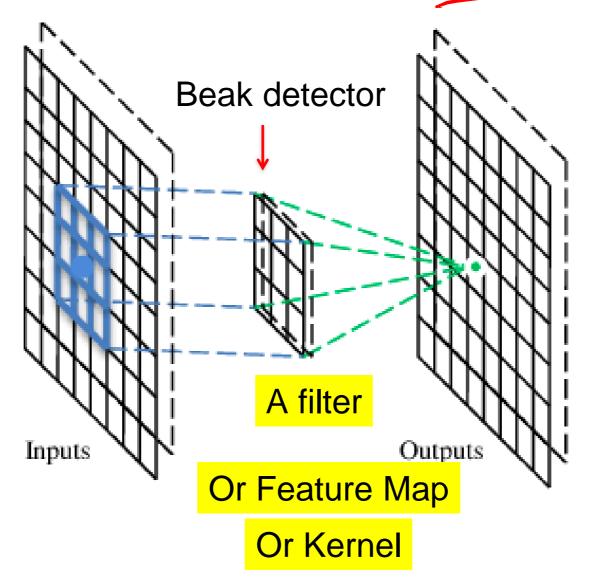


Same pattern appears in different places: They can be compressed! What about training a lot of such "small" detectors and each detector must "move around".



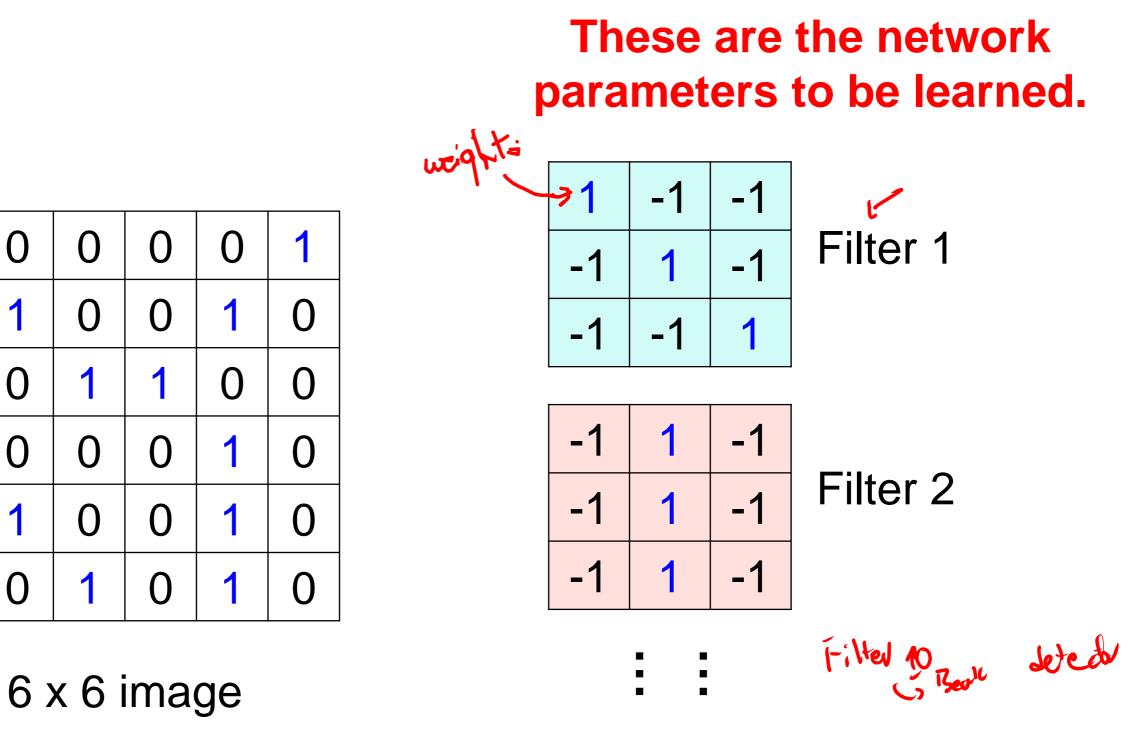
A convolutional layer

A CNN is a neural network with some convolutional layers (and some other layers). A convolutional layer has a number of filters that does convolutional operation. Neocognitron by Kunihiko Fukushima (1980).



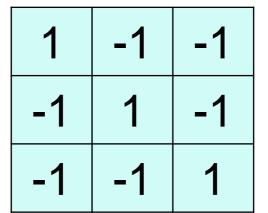
Convolution

()

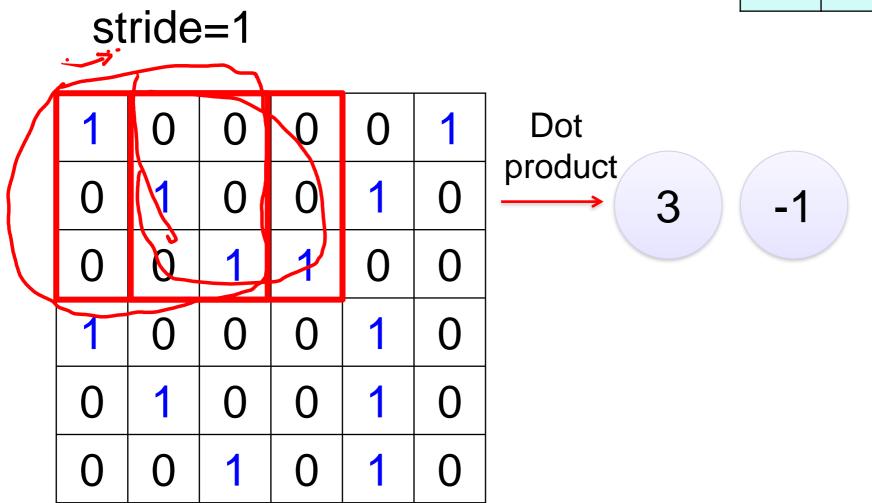


Each filter detects a small pattern (3 x 3).

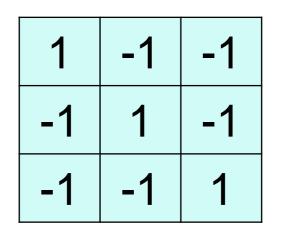
Convolution





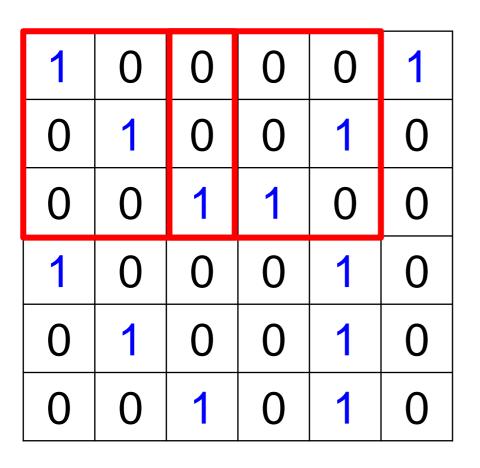


Convolution



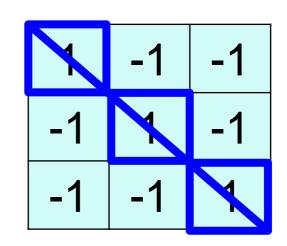
Filter 1

If stride=2



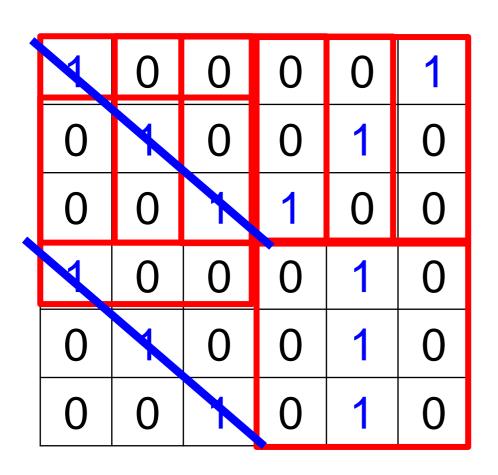
3 -3

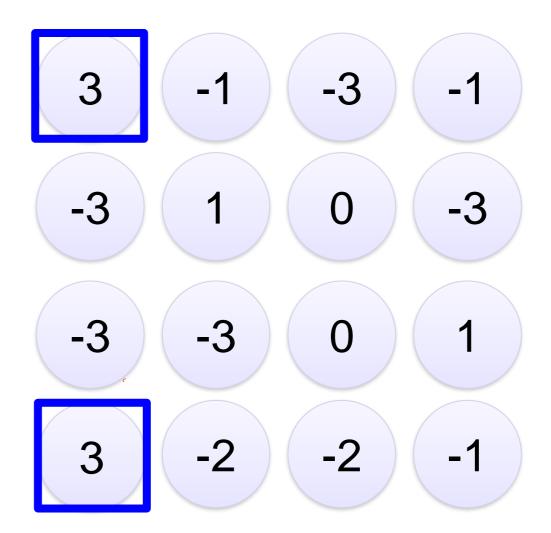
Convolution – diagonal edges?



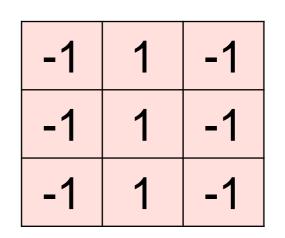
Filter 1

stride=1



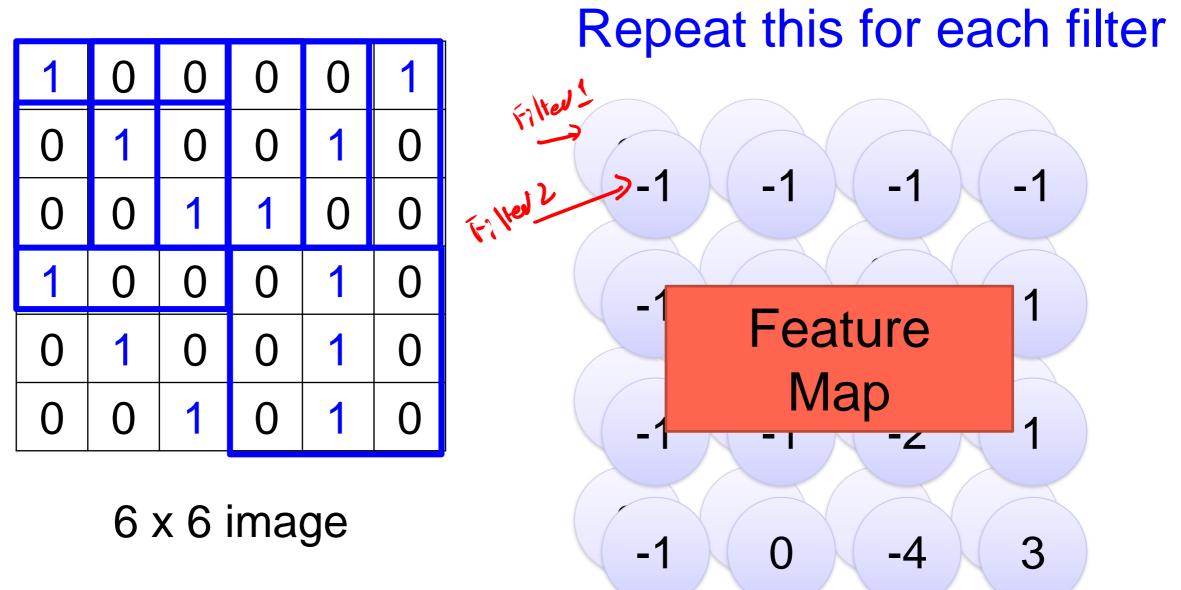


Convolution -Vertical edges?



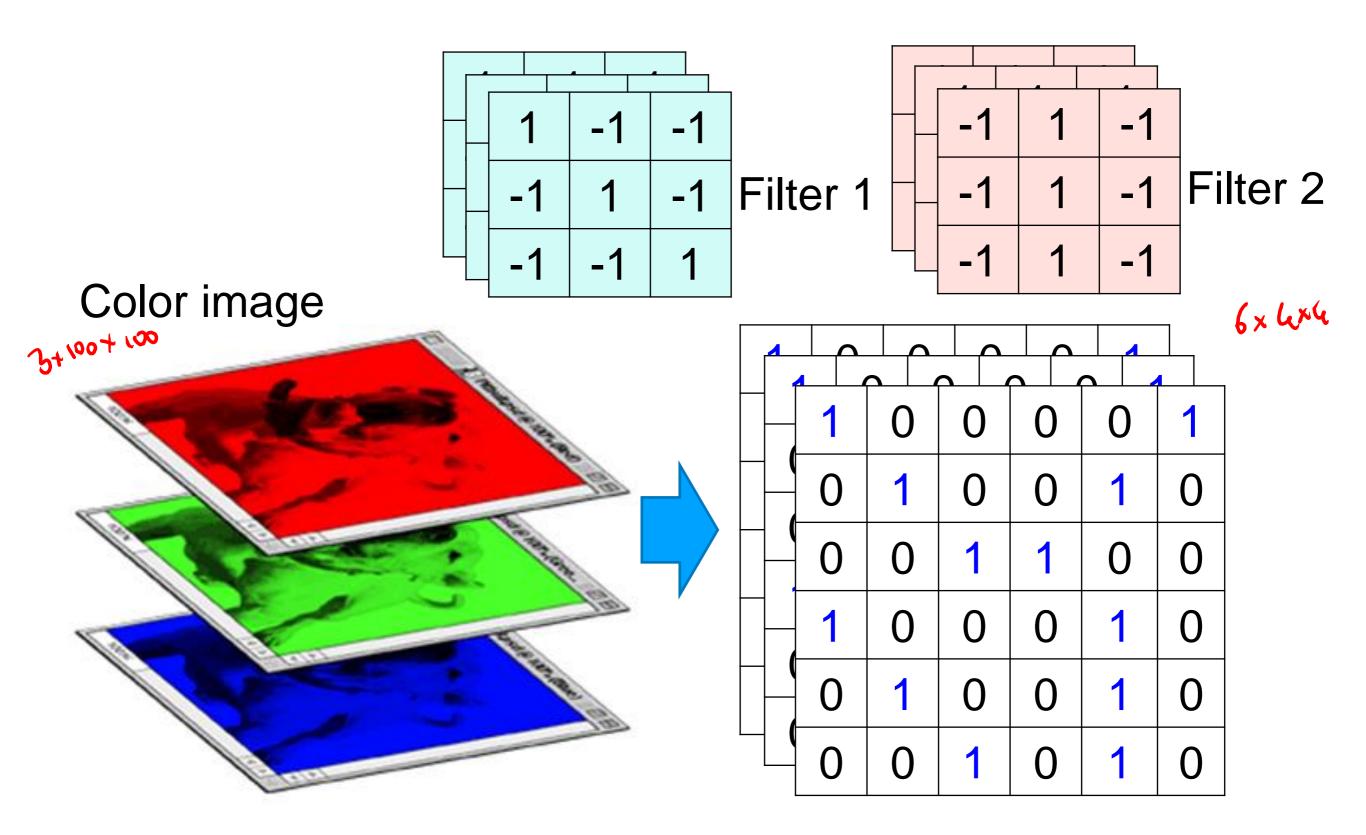
Filter 2



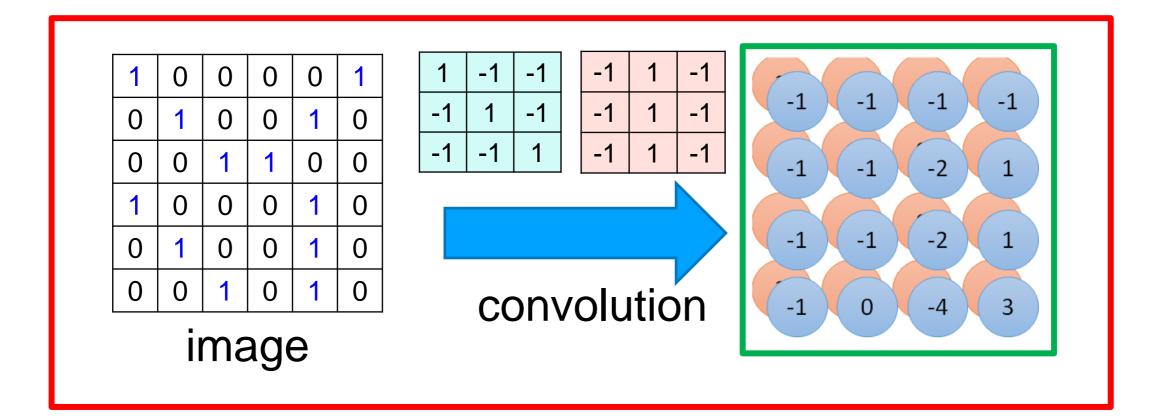


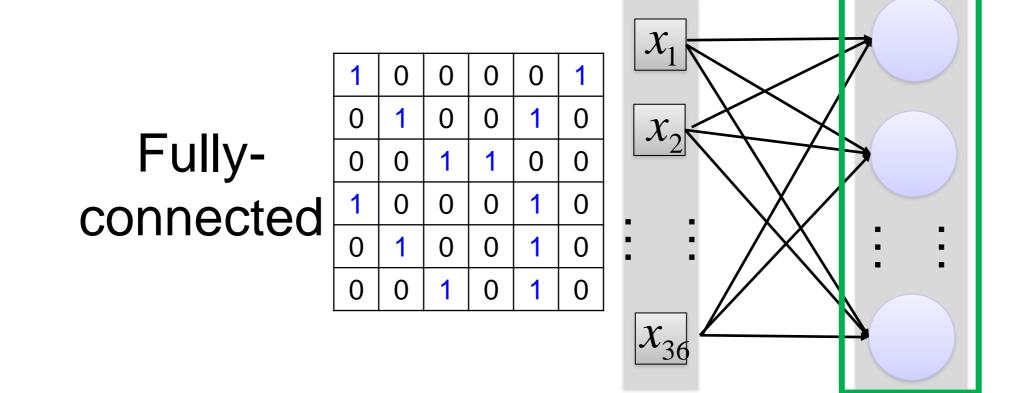
Two 4 x 4 images Forming 2 x 4 x 4 matrix

Color image: RGB 3 channels



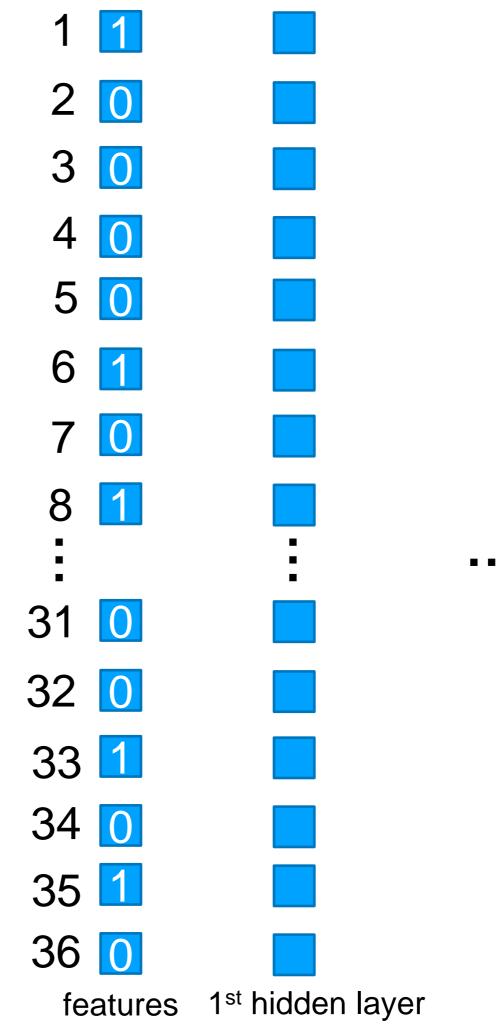
Convolution v.s. Fully Connected

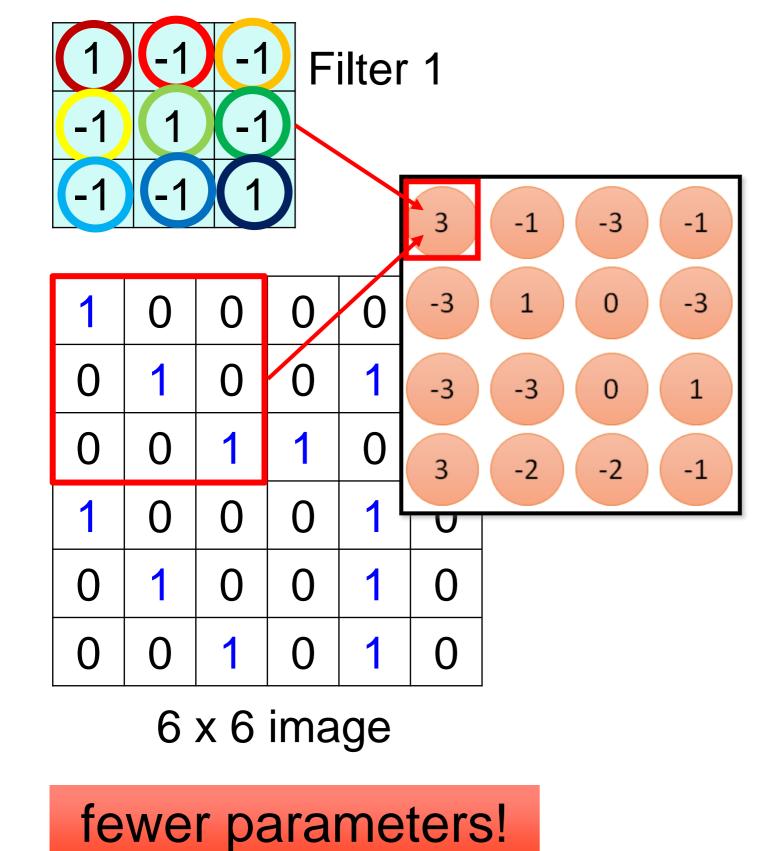


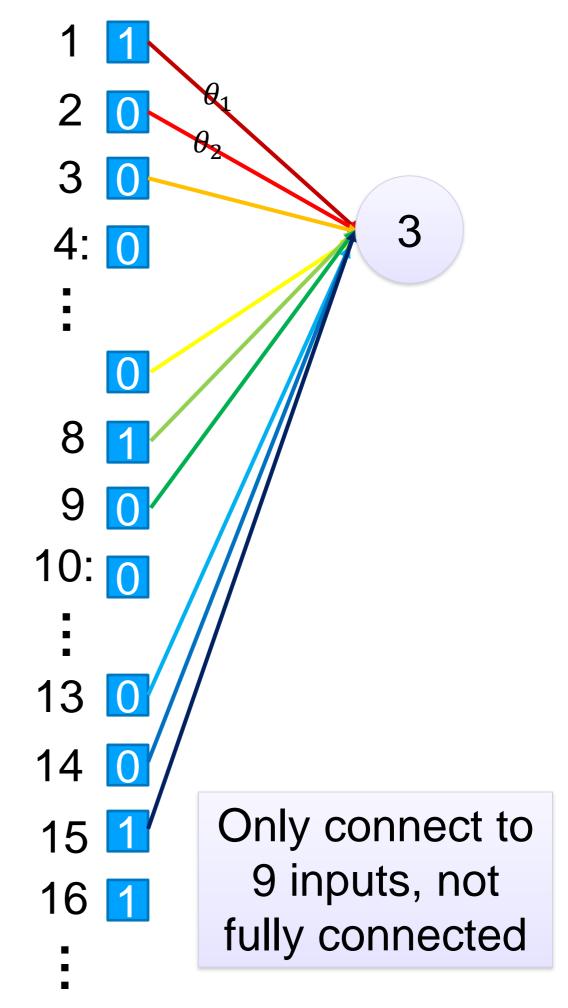


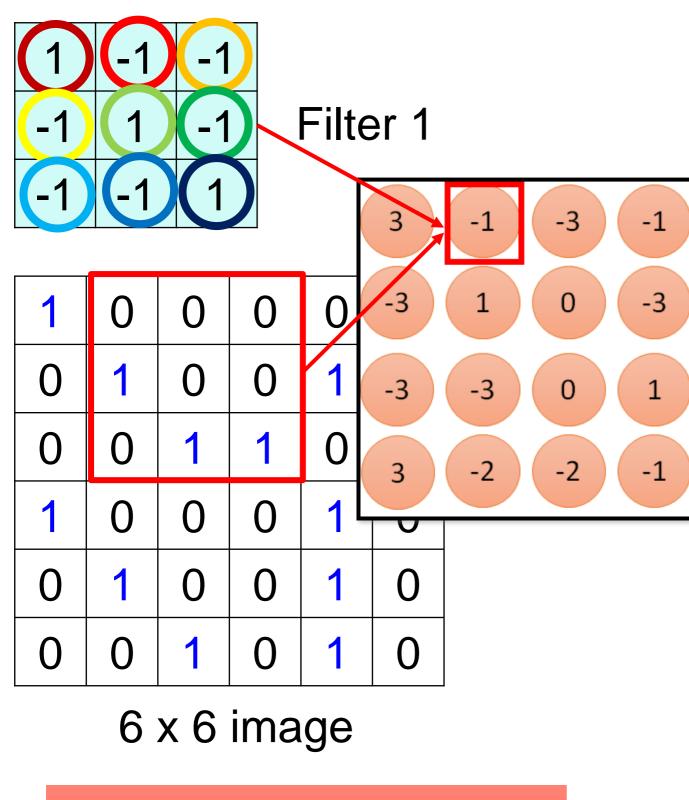
Conventional Fully Connected layers (FC layers)

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0



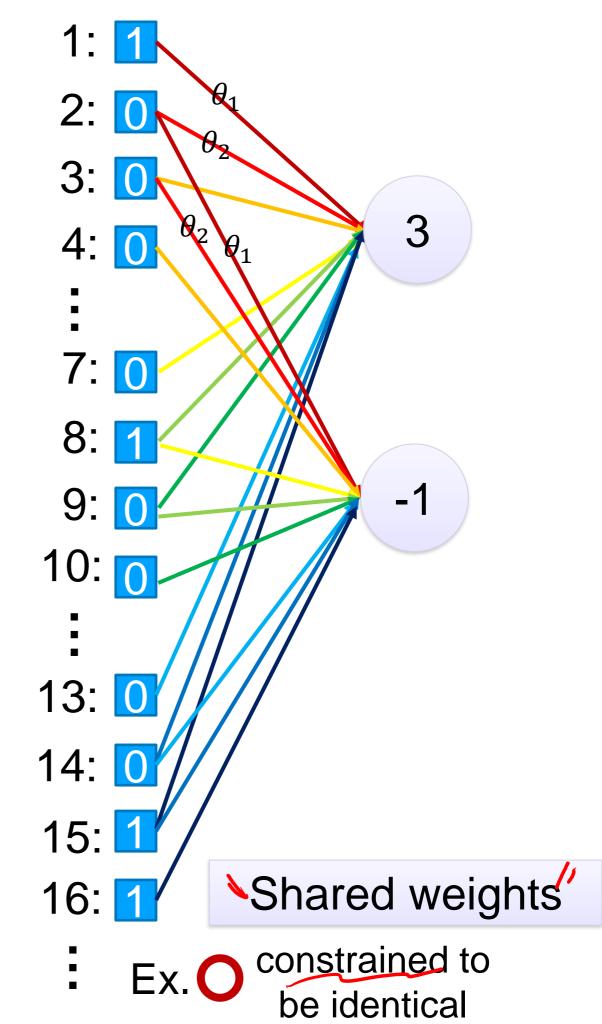


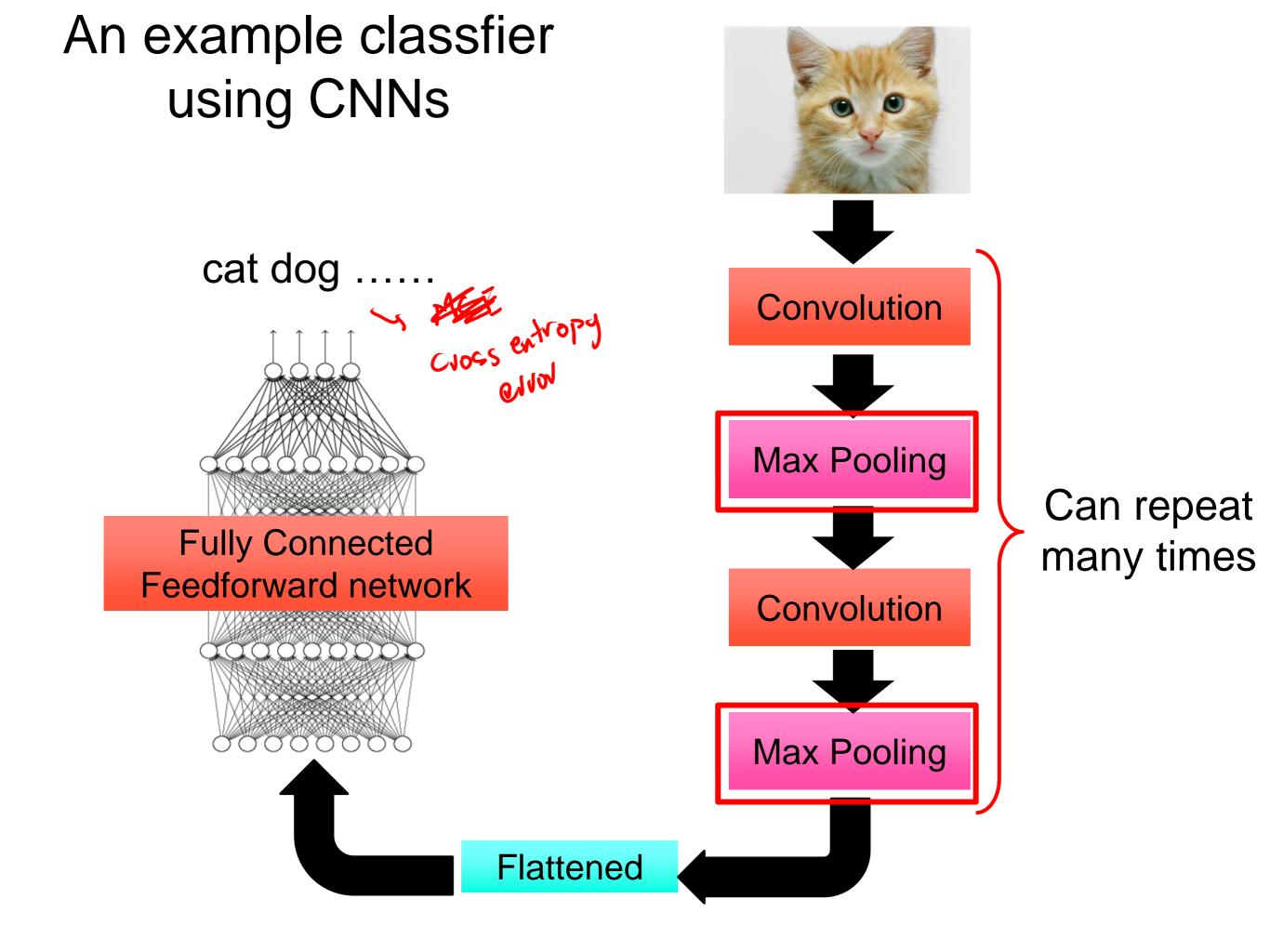




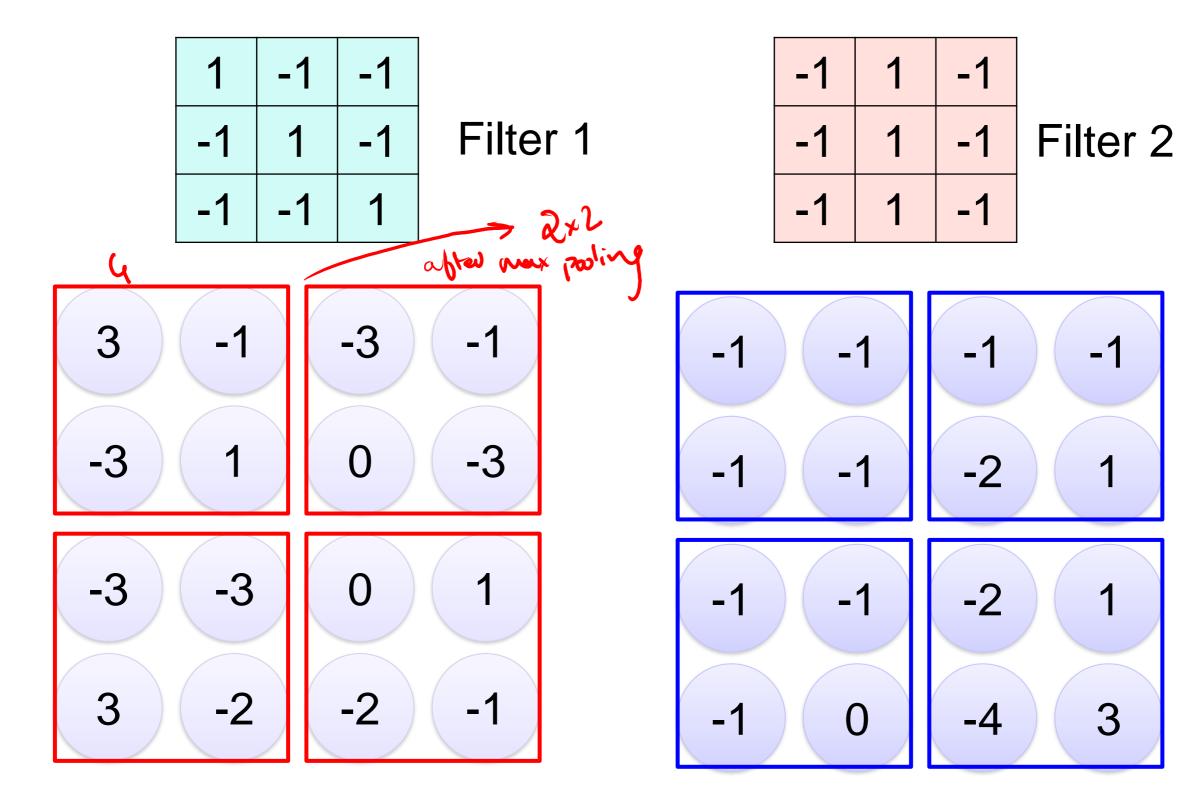
Fewer parameters

Even fewer parameters





Max Pooling



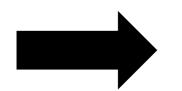
6

Why Pooling

 Subsampling pixels will not change the object bird



We can subsample the pixels to make image smaller

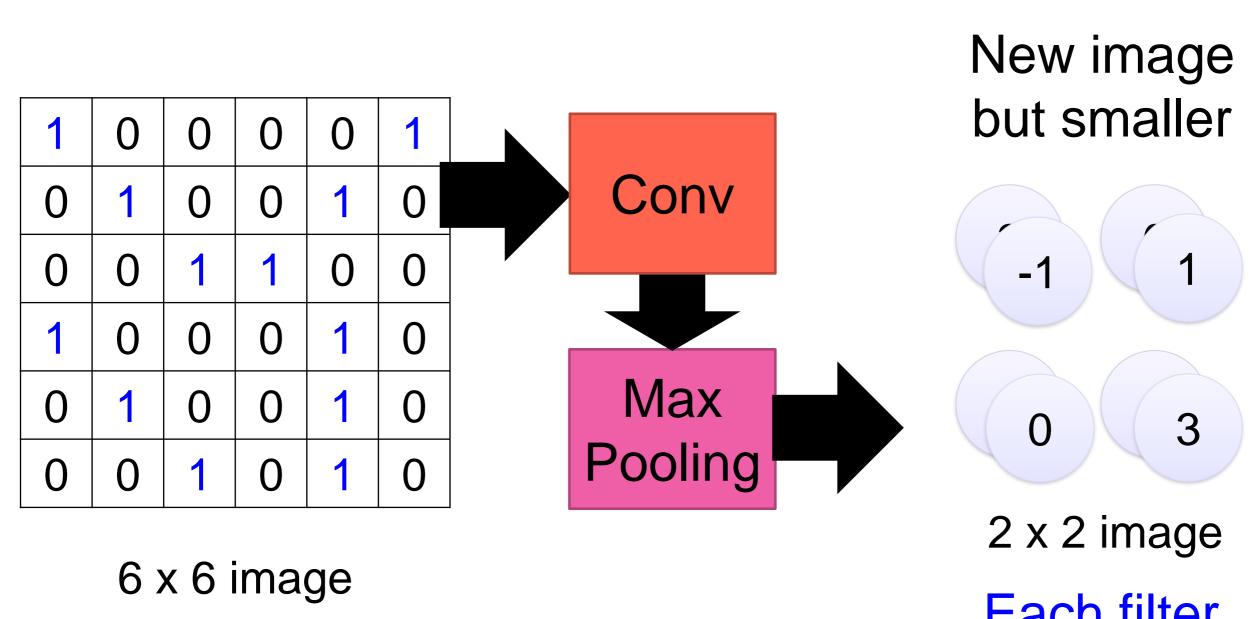


fewer parameters to characterize the image

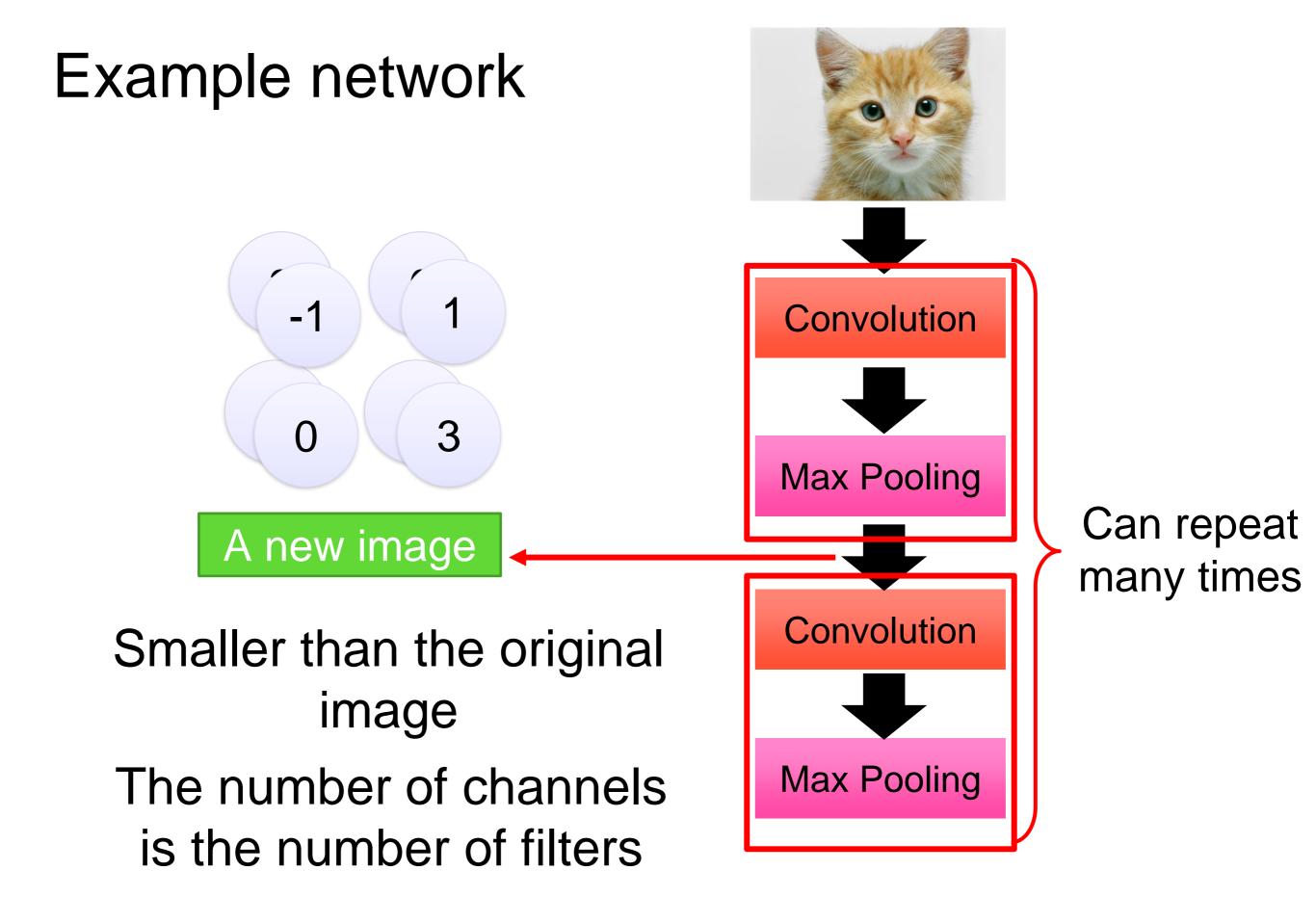
A CNN compresses a fully connected network in two ways:

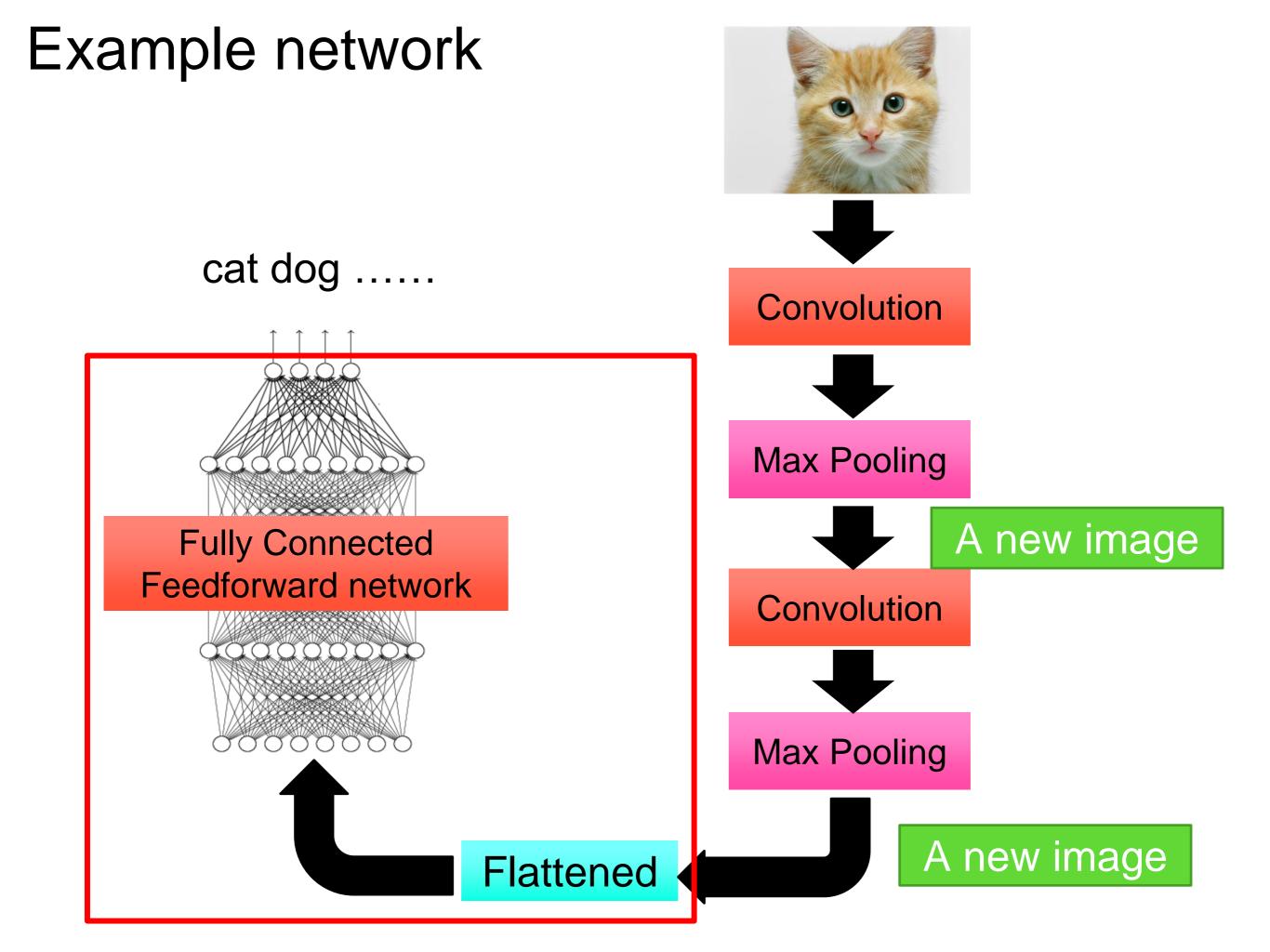
- Reducing number of connections
- Shared weights on the edges
- Moreover, Max pooling further reduces the complexity

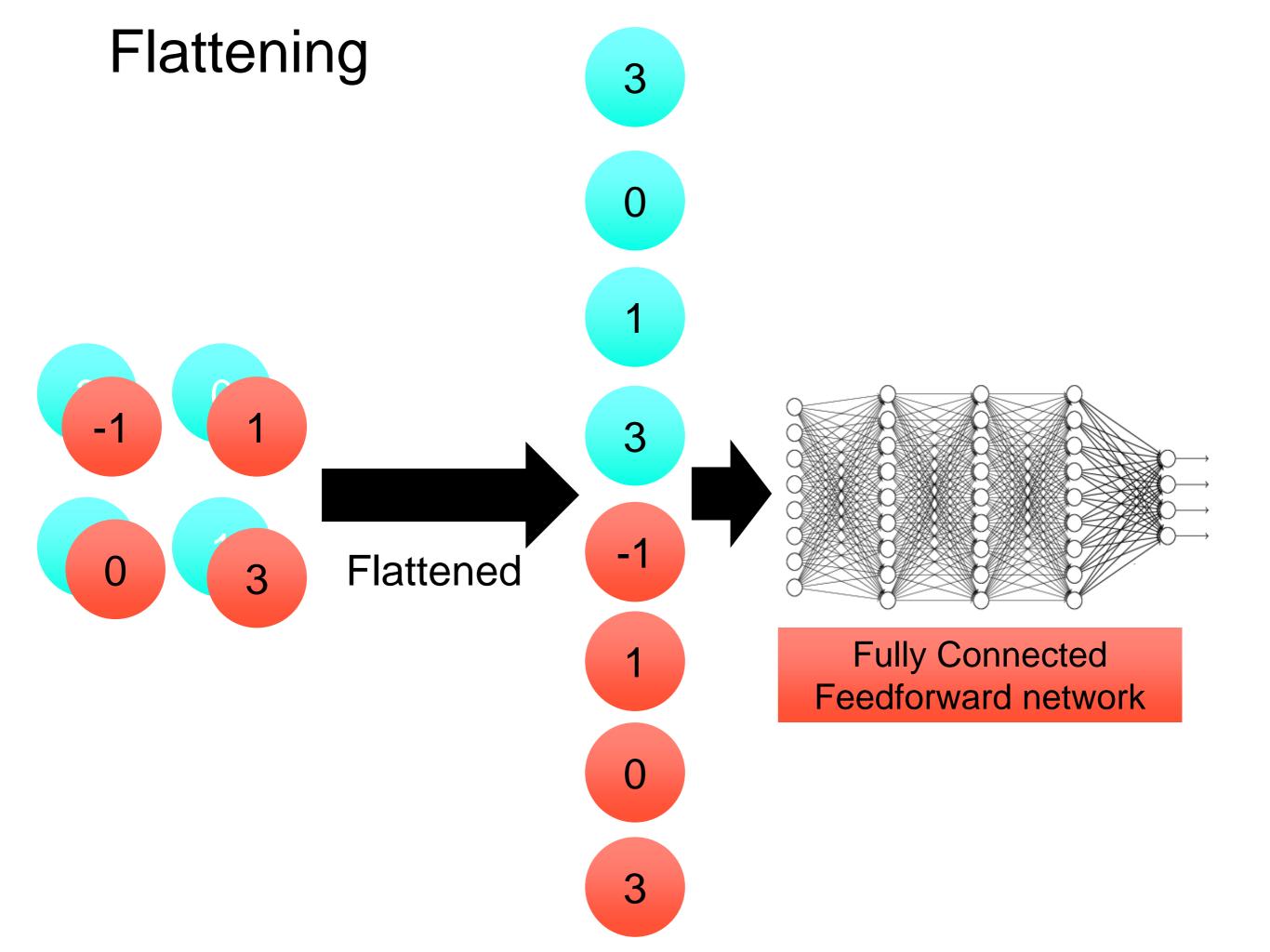
Max Pooling



Each filter is a channel

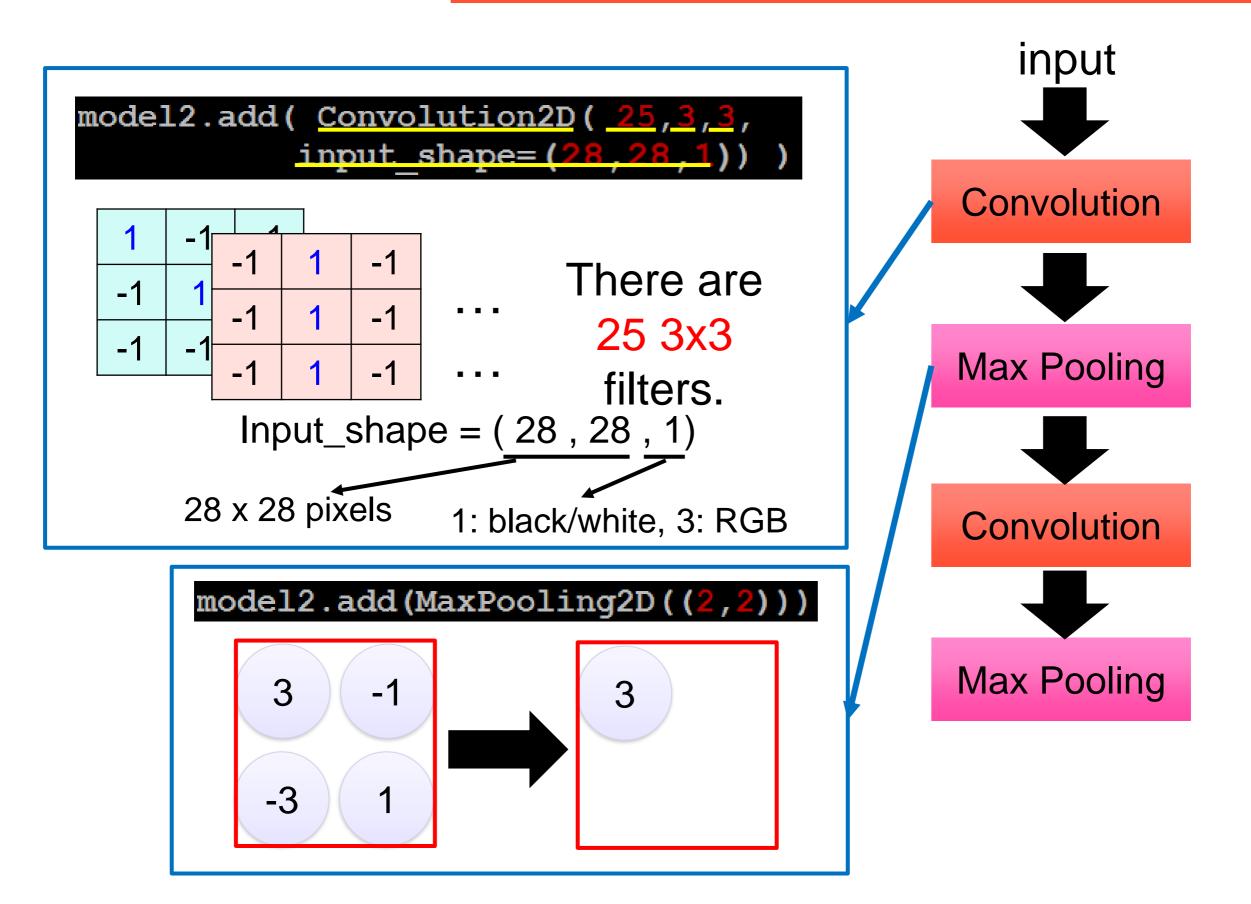






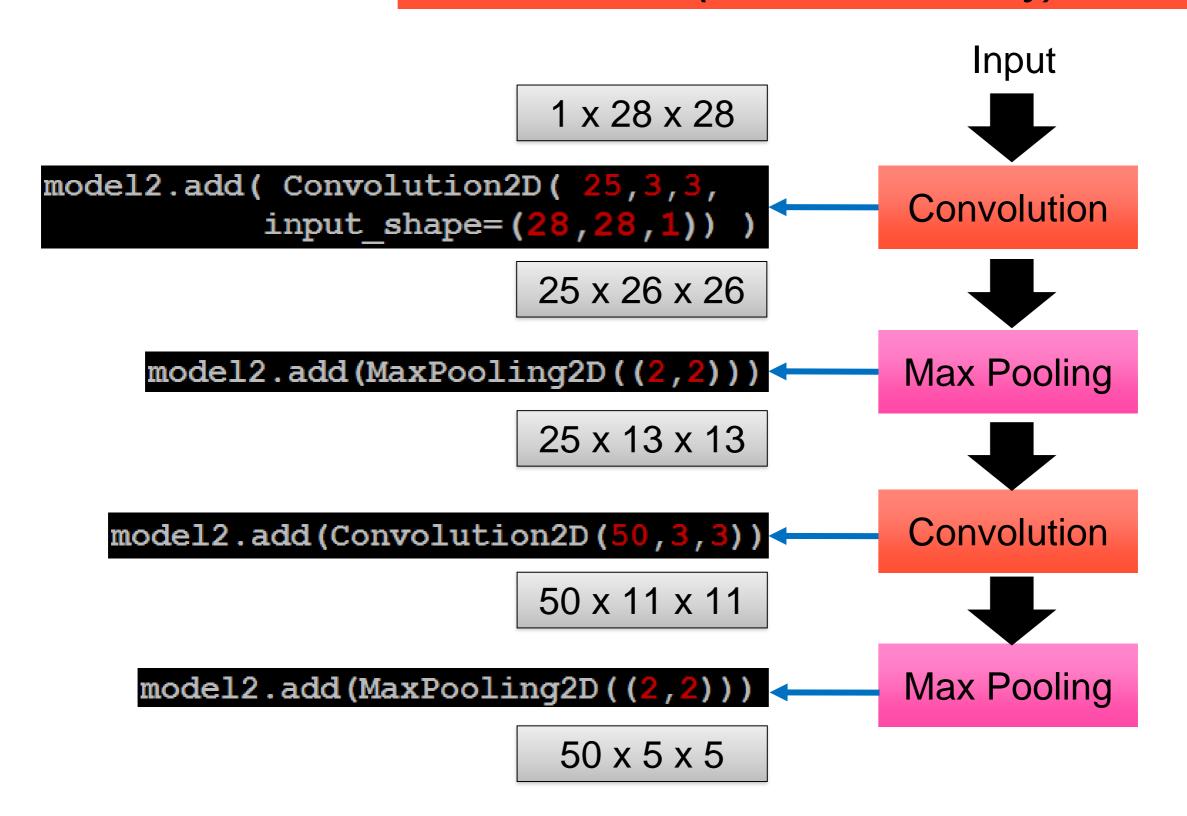
CNN in Keras

Only modified the *network structure* and *input* format (vector -> 3-D tensor)



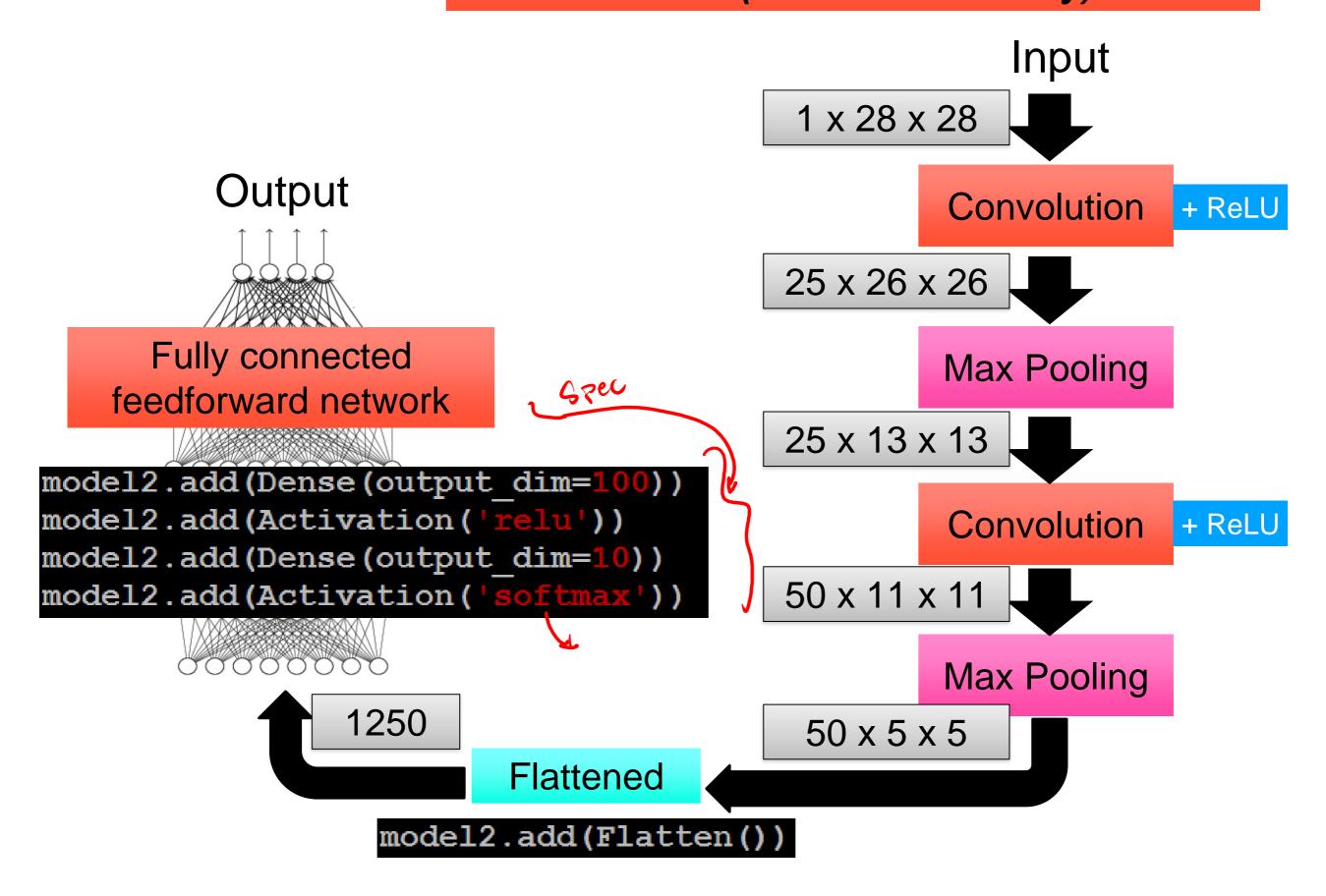
CNN in Keras

Only modified the *network structure* and *input* format (vector -> 3-D array)

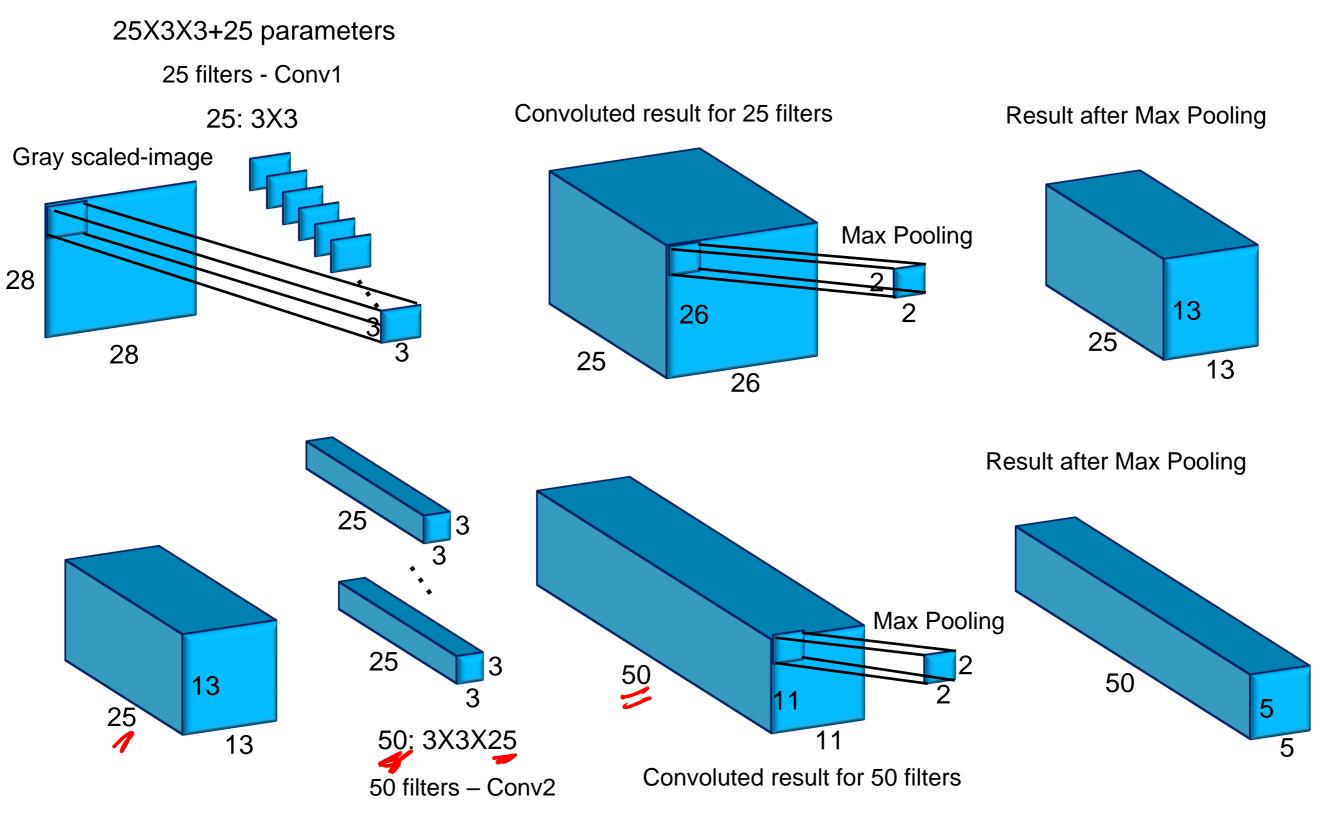




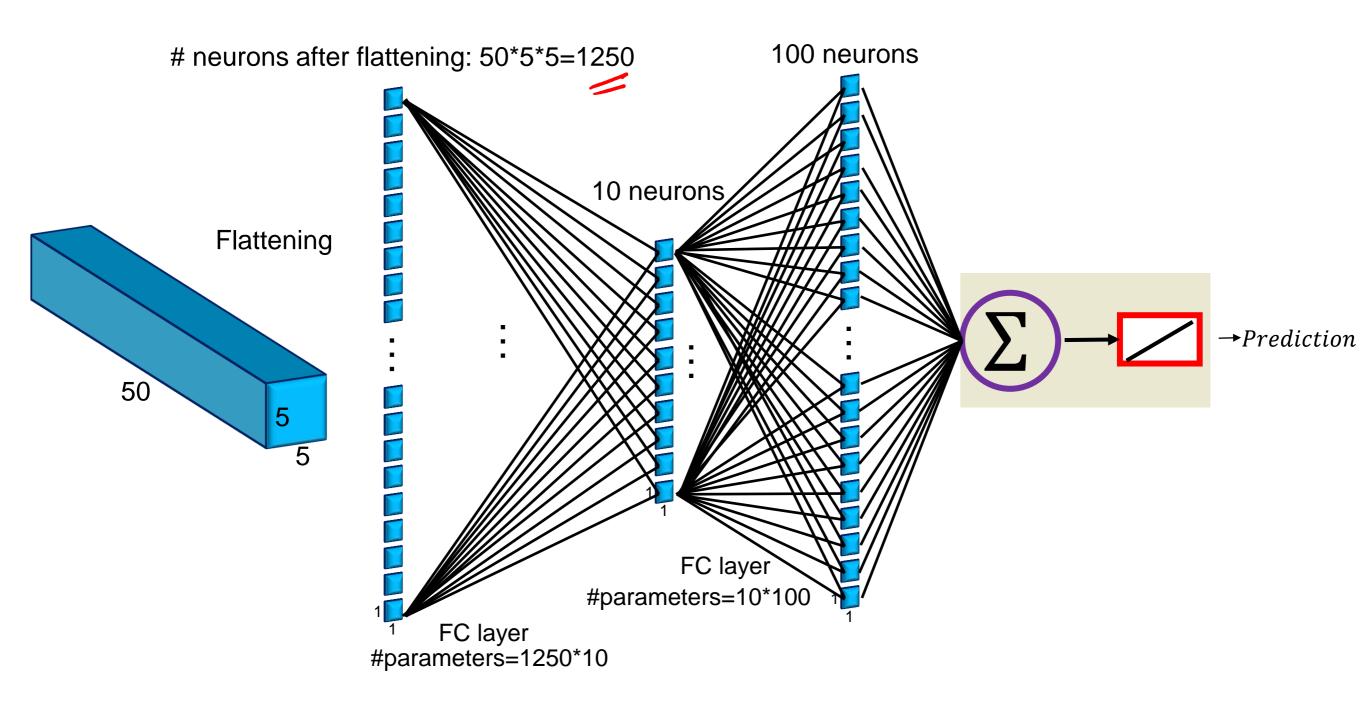
Only modified the *network structure* and *input* format (vector -> 3-D array)



Number of Parameters



50X3X3X25+50 parameters



10 CNN Architecture